Overview

This course covers interfacing of different critical input/output devices with controller and subsequently progress towards designing and programming of mobile robot to execute different tasks.

Participant profile

Any diploma/degree engineering students

Course contents

- Microcontroller overview
- Input/output device interfacing
- Analog signal processing
- Interrupt programming
- Timers/counters programming
- PWM signal, speed control, position control
- Serial communication

Objectives

After the completion of the course, the participant will able to understand/perform the following:

Able to interface different sensors, switches, relays, motors, devices like; Bluetooth, RF transmitter/receiver, etc to design different embedded system projects.

Able to design and program mobile robot to realise path follower, maze solver, tele-operated robot, mobile robot linear and rotational motion control using encoder, holonomic drive realization, etc.

Prerequisite

- Basic knowledge of different electronics and electrical components.
- Basic C/C++ programming.

Evaluation

- Quiz
- Theory and practice exam
- Experiential learning project

Time duration

- 36 Hours
- 6 Hours/Day

Mobile robot path planning Robot linear and rotational motion control

Mobile robot designing and

Tele-operation

programming

Holonomic drive realization

Teaching & learning media

- Multi-media presentation
- Live project demonstration

Fee

Rs 5500/-